

# Fast Global Tracking for the CBM Experiment at FAIR

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**MMCP**

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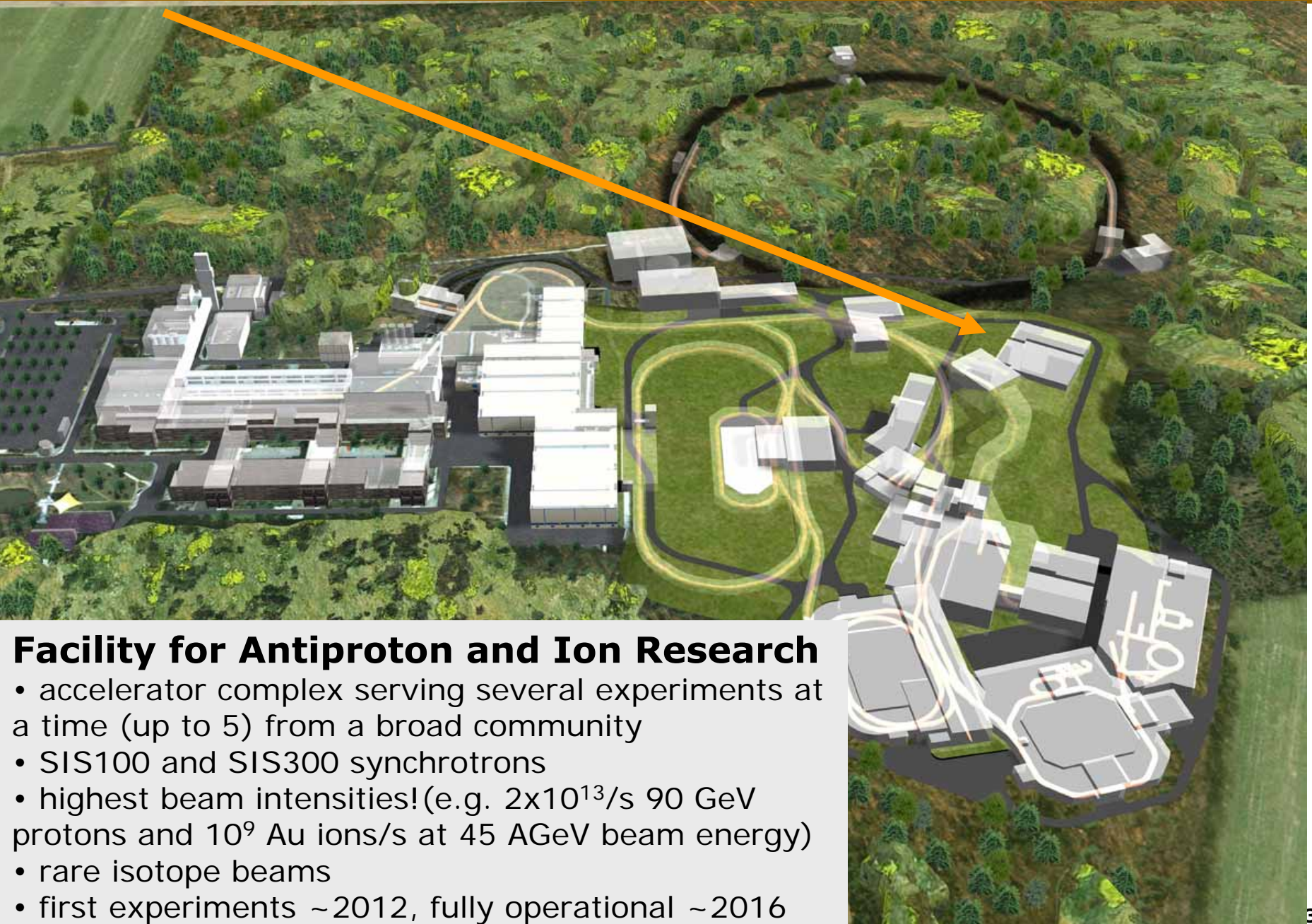
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# Outline

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- Introduction of CBM
- The CBM detector:
  - for muon identification
  - for electron identification
- Track reconstruction
  - challenges
  - solution
  - results
- Speed up of the algorithms

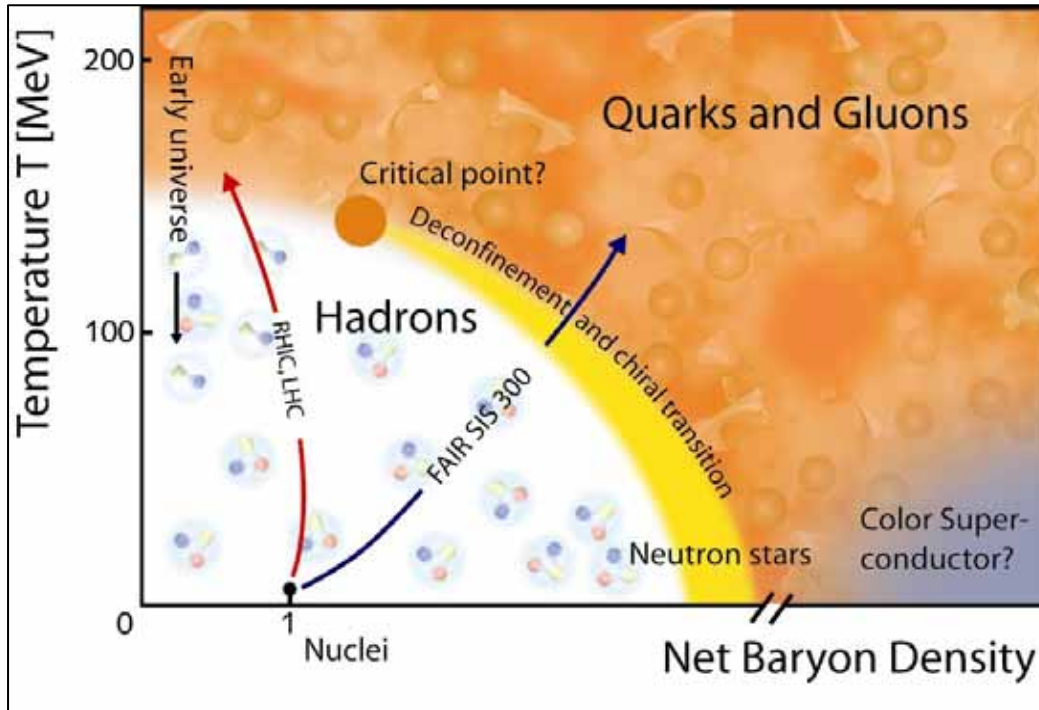
# CBM at FAIR



## Facility for Antiproton and Ion Research

- accelerator complex serving several experiments at a time (up to 5) from a broad community
- SIS100 and SIS300 synchrotrons
- highest beam intensities!(e.g.  $2 \times 10^{13}/s$  90 GeV protons and  $10^9$  Au ions/s at 45 AGeV beam energy)
- rare isotope beams
- first experiments ~2012, fully operational ~2016

# CBM physics topics

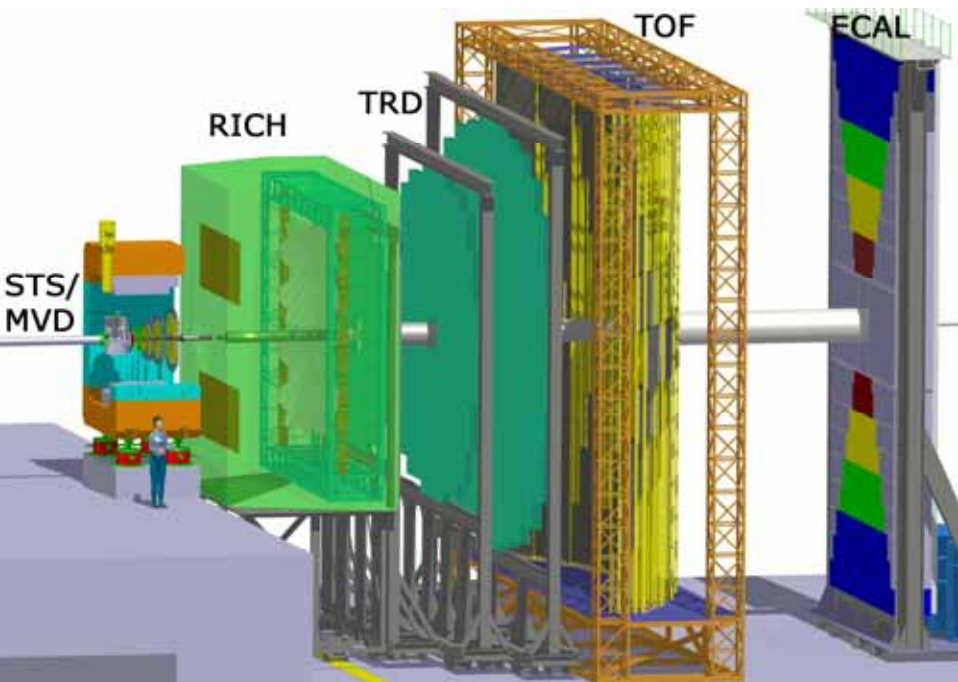


*Exploration of the QCD phase diagram in regions of high baryon densities and moderate temperatures.*

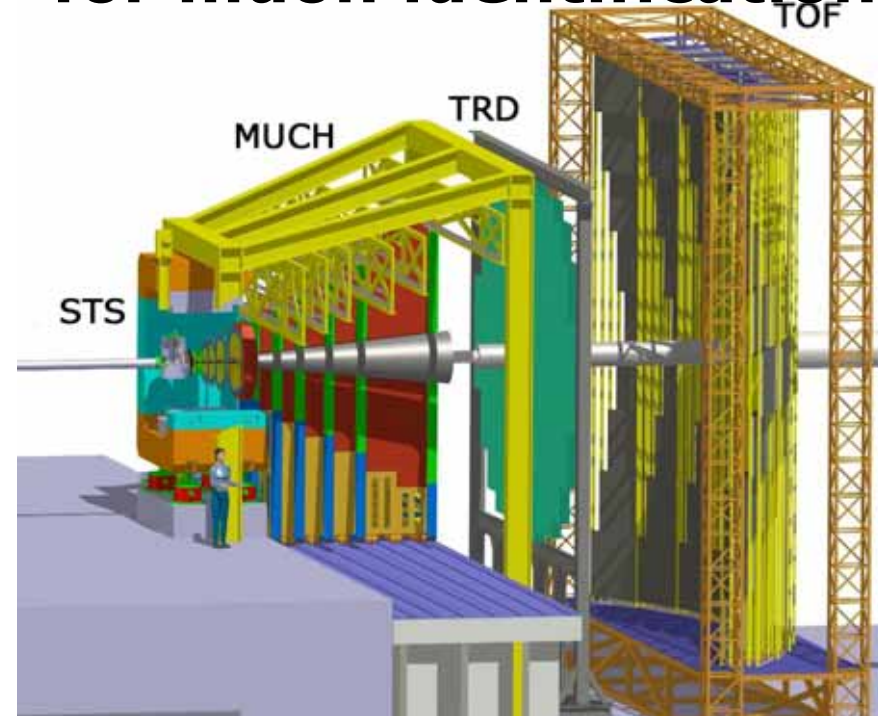
Physics Topics	Observables
<b>In medium modifications of hadrons</b>	$\rho, \omega, \phi \rightarrow \mu^+ \mu^- (e^+ e^-)$ $D^0, D^\pm, D_{s'}^\pm, \Lambda_c$
<b>Deconfinement phase transition, charm production at threshold</b>	$K, \Lambda, \Sigma, \Xi, \Omega$ $D^0, D^\pm$ $J/\Psi, \Psi' \rightarrow \mu^+ \mu^- (e^+ e^-)$
<b>Critical point</b>	<b>Event by event fluctuations</b>

# The CBM detector

for electron identification



for muon identification



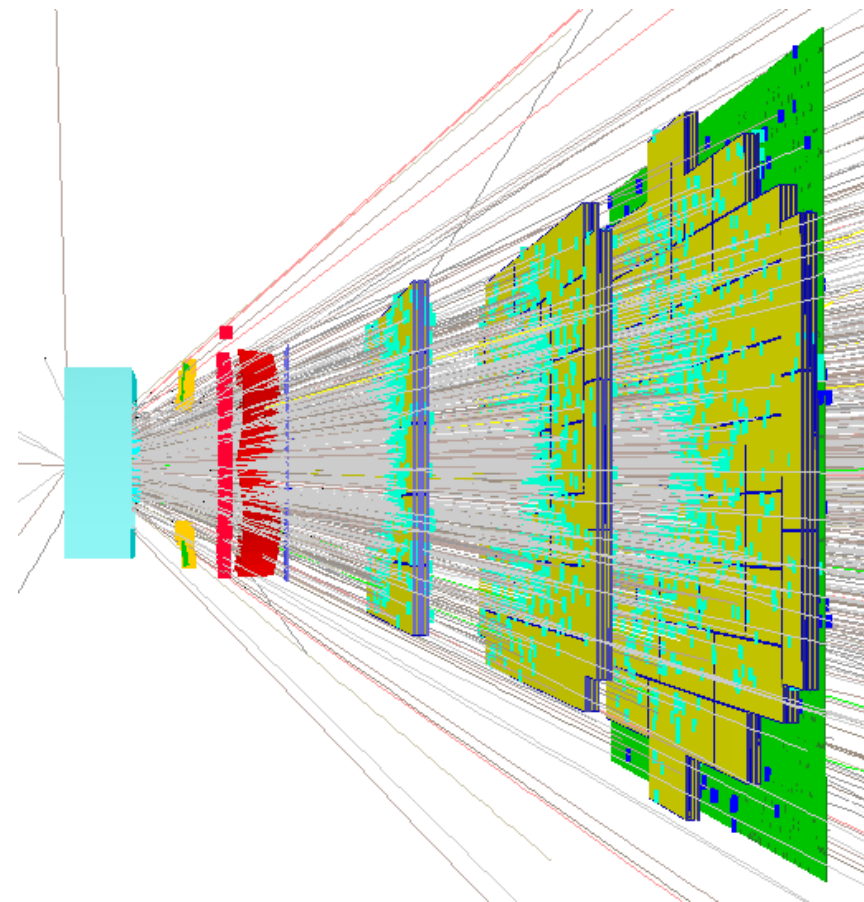
- STS:** track, vertex and momentum reconstruction
- MVD:** determination of secondary vertices
- RICH:** electron identification
- MUCH:** muon identification
- TRD:** global tracking and identification of electrons
- TOF:** time of flight measurement for hadron identification
- ECAL:** measurement of photons and neutral particles

# Challenges for global tracking

- comprehensive measurement of hadron and lepton production in  $pp$ ,  $pA$  and  $AA$  collisions from **8-45 AGeV** beam energy
- fixed target experiment

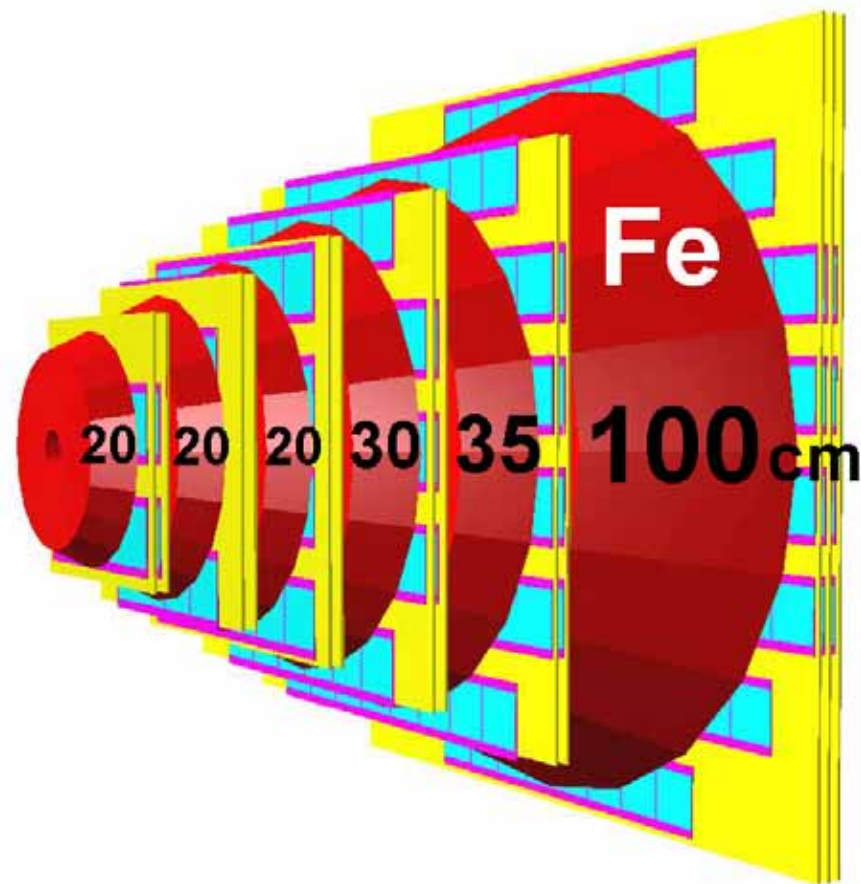
for CBM:

- up to **800** charged particles per reaction
- signal particles very rare ( $\langle J/\psi \rangle \sim 10^{-6}$ , branching ratio of low-mass vector mesons  $\sim 10^{-5}$ )
- complex detector structure, overlapping sensors, dead zones in the detector
- large material budget



Central Au+Au  
collision at 25 AGeV  
(UrQMD + GEANT3)

# The Muon detector (MUCH)



Choose alternating detector-absorber layout for continuous tracking of the muons through the absorber

## Measurements of:

— *Low mass vector mesons*  
**5 Fe** absorbers (**125 cm**)  
 $7.5 \lambda_I, p > 1.5 \text{ GeV}/c$

- - - *Charmonium*  
**6 Fe** absorbers (**225 cm**)  
 $13.5 \lambda_I, p > 2.8 \text{ GeV}/c$

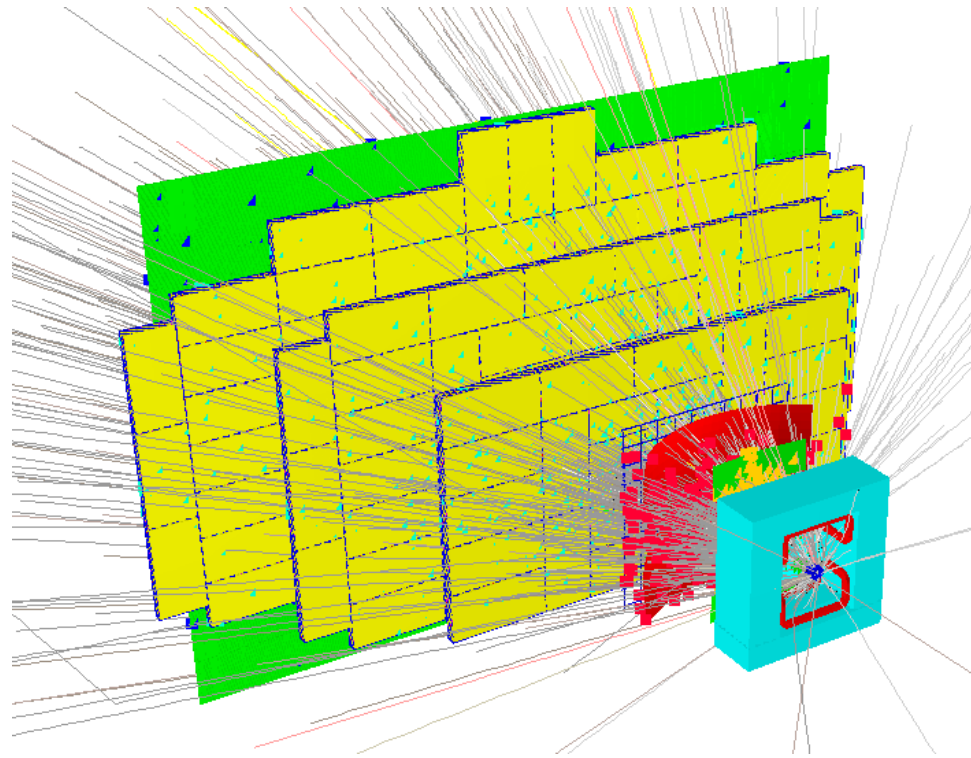
**2(3)** detector stations between the absorbers

## Detector challenges:

- High hit density (up to 1 hit per  $\text{cm}^2$  per event)
  - High event rates ( $10^7$  events/s)
  - Position resolution  $< 300 \mu\text{m}$
- use pad readout (e.g. GEMs), minimum pad size  $1.4 \times 2.8 \text{ mm}^2$ .

# The TRD

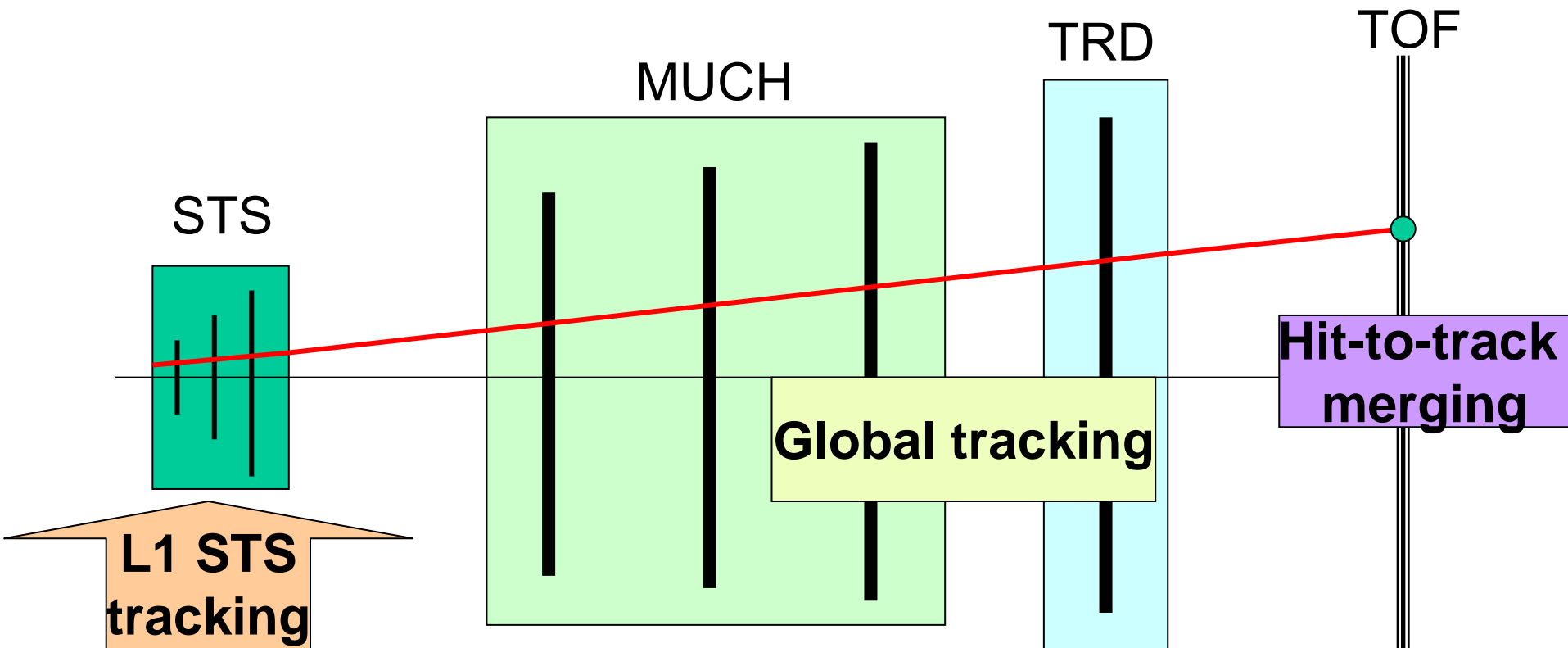
- Tracking and electron identification via energy losses
- **12** identical layers grouped in **3** stations
- Layer=radiator+MWPC readout
- Stations: 5m, 7m, 9m
- Pad size: **0.03cm-0.05cm** across the pad and **0.27cm-3.3cm** along the pad





# Global tracking

- STS tracking  $\rightarrow$  Fast Cellular Automaton algorithm (see talk by I.Kisel)
- Global Tracking + TOF hit to track merging



# Track propagation

- **Extrapolation.** Two models:
  - Straight line in case of absence of magnetic field.
  - Solution of the equation of motion in a magnetic field with the 4<sup>th</sup> order Runge-Kutta method, with a parallel integration of the derivatives.

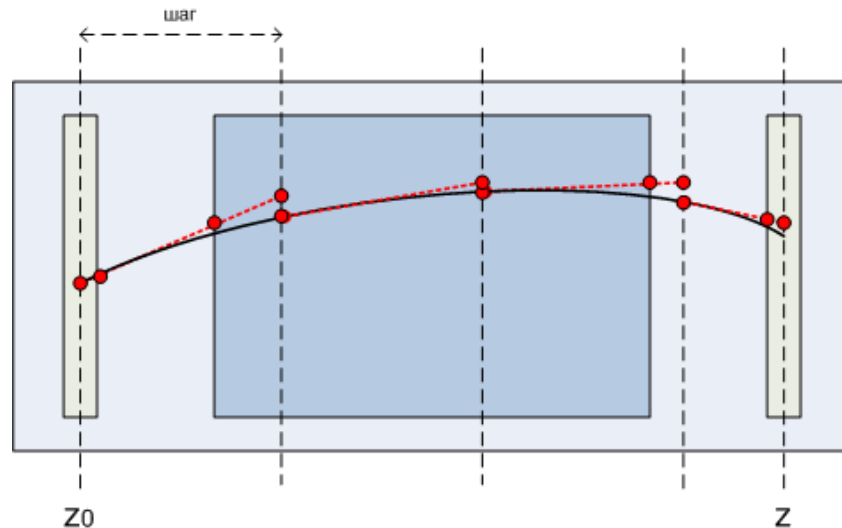
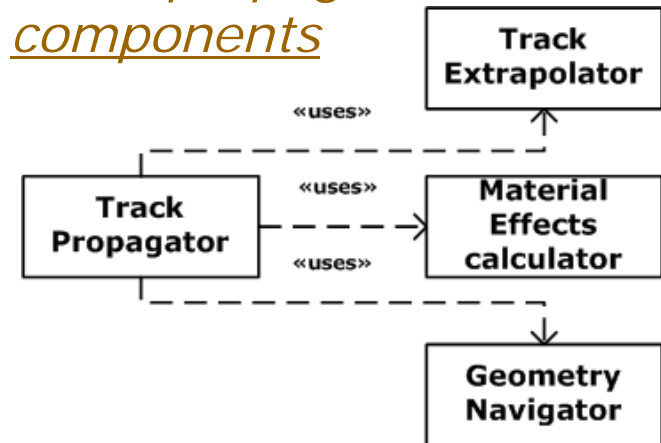
- **Material Effects.**

- Energy loss (ionization: Bethe-Bloch, bremsstrahlung: Bethe-Heitler, pair production)
- Multiple scattering (Gaussian approximation)

- **Navigation.**

- Based on the *ROOT TGeoManager*.

## Track propagation components



## The Algorithm:

Trajectory is divided into steps. For each step:

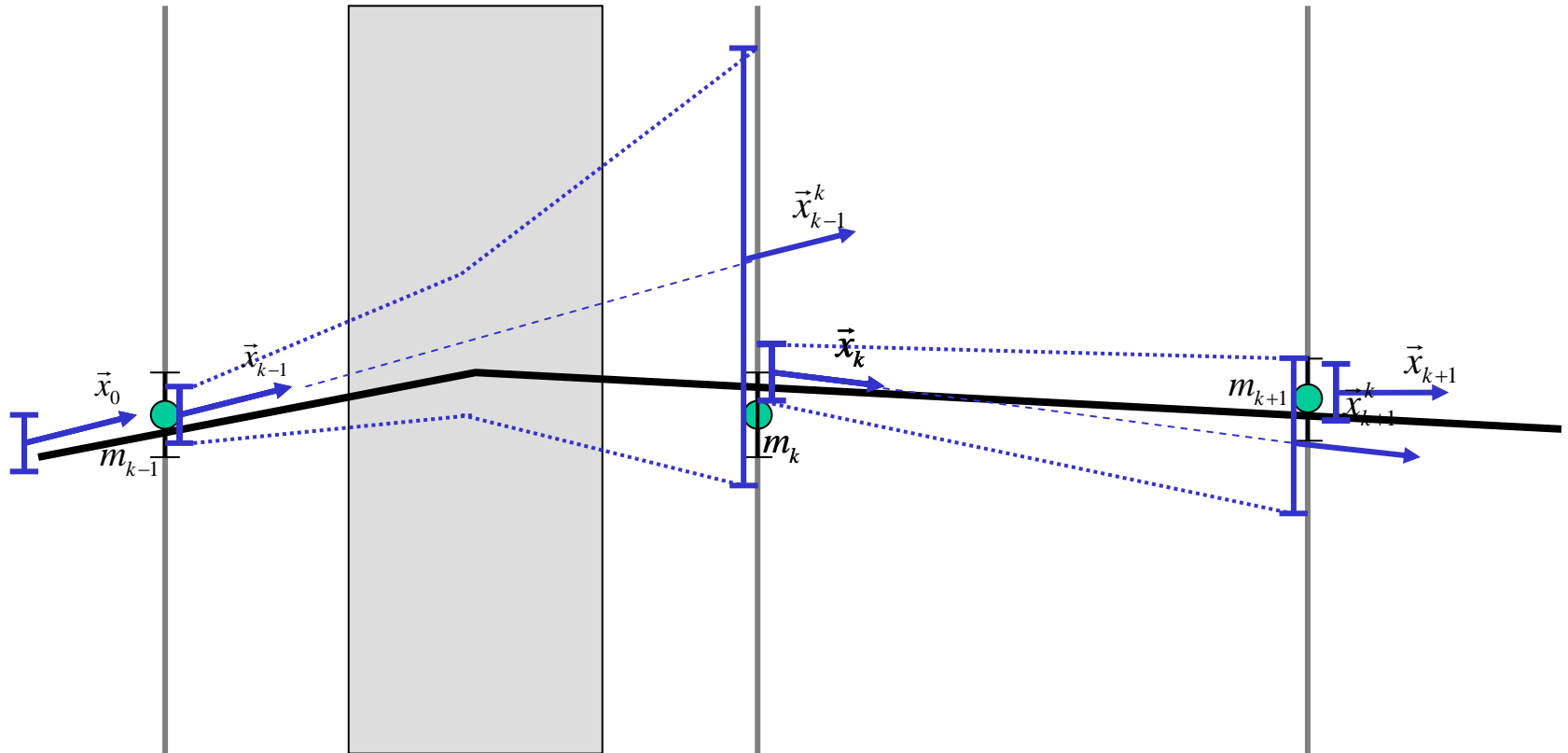
- — — — Straight line approximation for finding intersections with different materials (geometry navigator)
- — — — Geometrical extrapolation of the trajectory

Material effects are added at each intersection point

# Algorithm of Global Tracking

- Initial seeds are tracks reconstructed in STS (L1 tracking)
- Tracking is based on
  - Track following
  - Kalman Filter (KF)
  - Validation gate
  - Different hit-to-track association techniques
- Two main steps:
  - Tracking
  - Global track selection

# Track following and KF



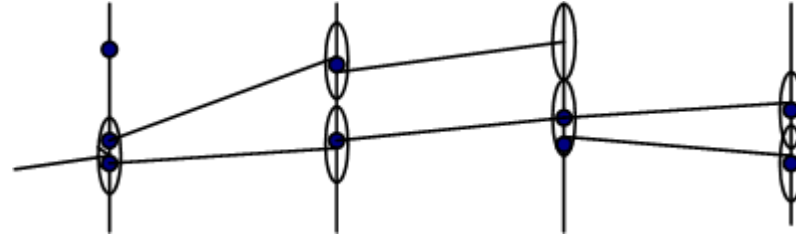
# Validation gate

- Rejection of improbable hit-to-track pairings: select true hits with high degree of confidence
- Validation gate at station  $k$ :  $v_k = r_k R^{-1} r_k^T < d$ 
  - $d$  is the threshold for rejecting the correct hit with a certain probability (depends on number of degrees of freedom, take from Chi2-tables)

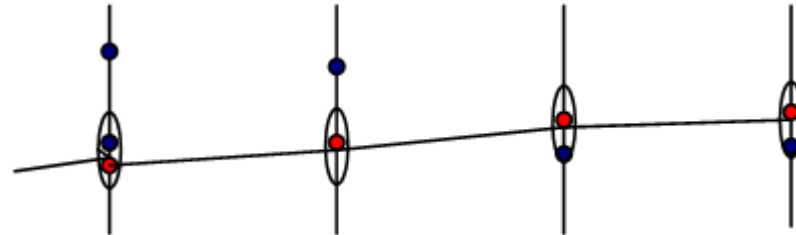
Degrees of Freedom	Probability										
	0.95	0.90	0.80	0.70	0.50	0.30	0.20	0.10	0.05	0.01	0.001
1	0.004	0.02	0.06	0.15	0.46	1.07	1.64	2.71	3.84	6.63	10.83
2	0.10	0.21	0.45	0.71	1.39	2.41	3.22	4.60	5.99	9.21	13.82
3	0.35	0.58	1.01	1.42	2.37	3.66	4.64	6.25	7.82	11.34	16.27
4	0.71	1.06	1.65	2.20	3.36	4.88	5.99	7.78	9.49	13.28	18.47
5	1.14	1.61	2.34	3.00	4.35	6.06	7.29	9.24	11.07	15.09	20.52
6	1.63	2.20	3.07	3.83	5.35	7.23	8.56	10.64	12.59	16.81	22.46
7	2.17	2.83	3.82	4.67	6.35	8.38	9.80	12.02	14.07	18.48	24.32
8	2.73	3.49	4.59	5.53	7.34	9.52	11.03	13.36	15.51	20.09	26.12
9	3.32	4.17	5.38	6.39	8.34	10.66	12.24	14.68	16.92	21.67	27.88
10	3.94	4.86	6.18	7.27	9.34	11.78	13.44	15.99	18.31	23.21	29.59
	Nonsignificant								Significant		

# Different hit-to-track assignment

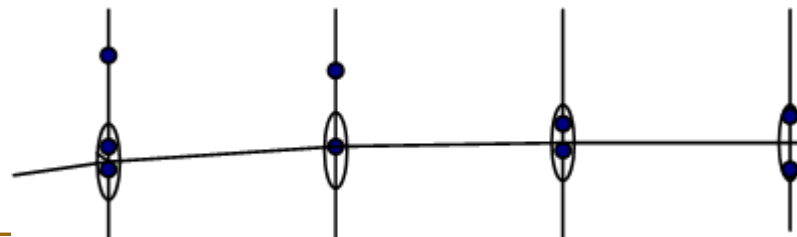
- Branching
  - Branch is created for each hit in the *validation gate*.



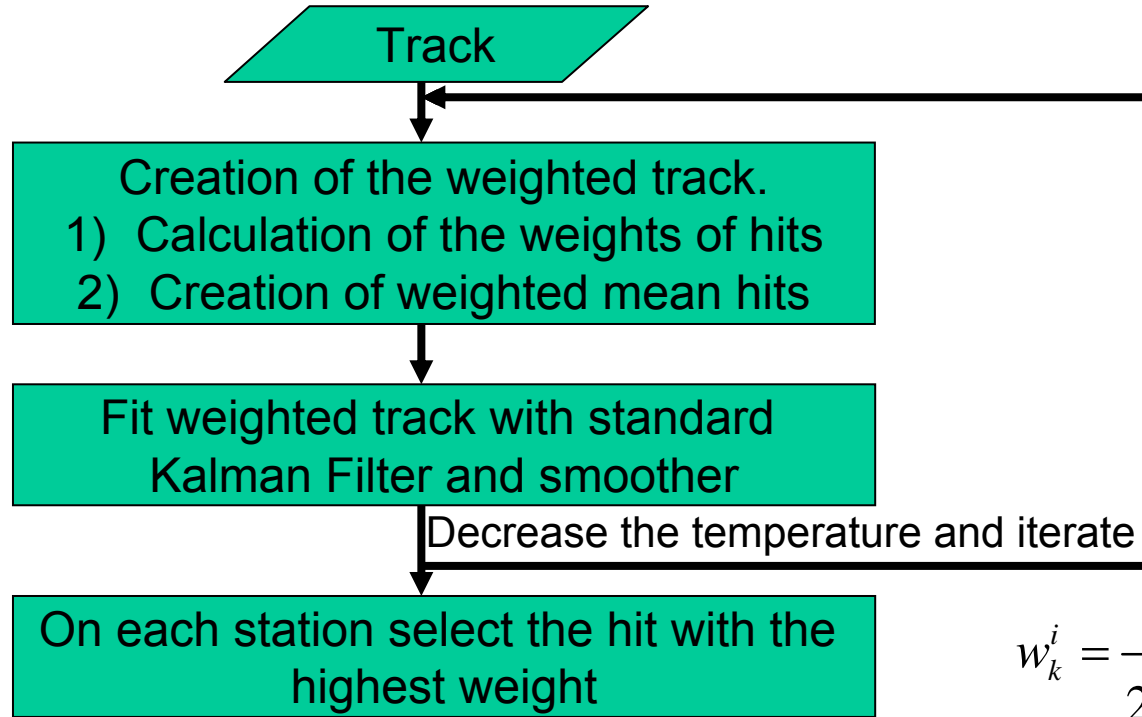
- Nearest Neighbor
  - The closest by a Euclidean *statistical distance* hit from a *validation gate* is assigned to track.



- Weighting
  - No track splitting, it collects all the hits in the *validation gate*.



# Iterative hit selection and track fit

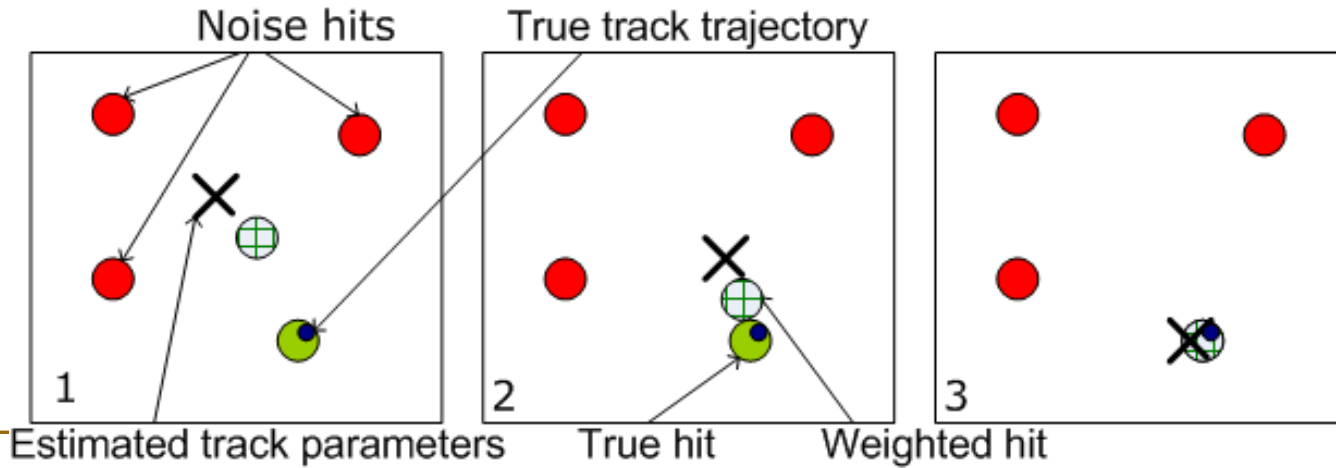


## Weight function:

- For the 1<sup>st</sup> iteration weights are the same
- Starting from the 2<sup>nd</sup> iteration, weights are proportional to the *multivariate Gaussian distribution* and include temperature parameter T

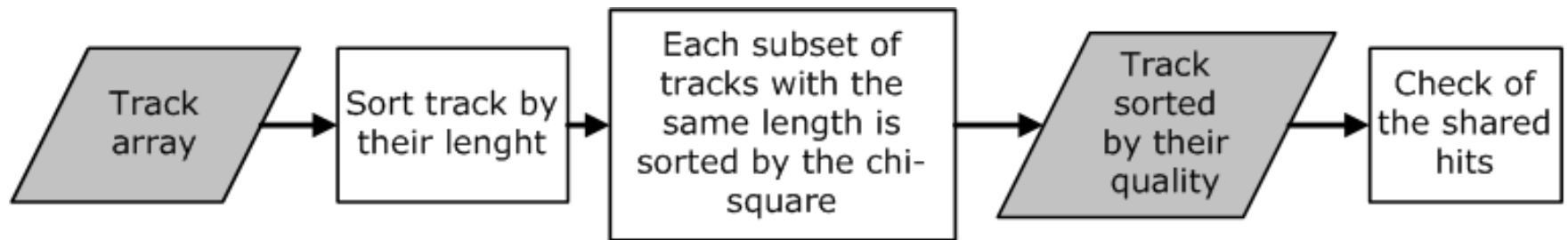
$$w_k^i = \frac{1}{2\pi * T |V_k^i|^{1/2}} \exp\left(-\frac{1}{2T} r_k^i (R_k^i)^{-1} (r_k^i)^T\right)$$

## How simulated annealing works



# Track selection

- aim: remove clone and ghost tracks
- Tracks are sorted by their quality, obtained by chi-square and track length



- Check for shared hits
  - loop over tracks list which is sorted by quality
  - collect used hits
  - check for each new track the number of shared hits: if too many – reject track

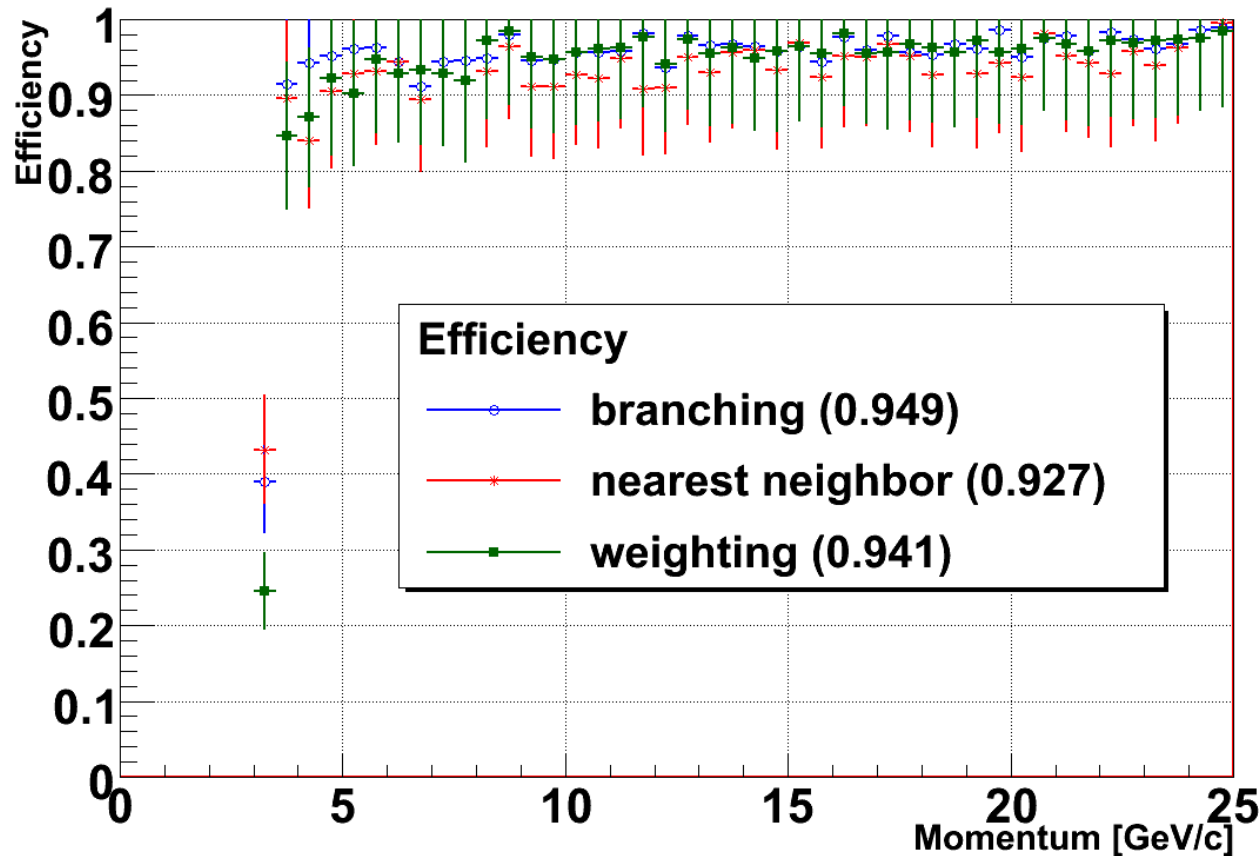


# Comparison of tracking methods

CBM setup for  
*muon*  
reconstruction

## Events

1000 UrQMD at  
25 AGeV + 10  
mu in each event



# Speed up [1]: number of branches

- **Motivation:** The main problem with branching algorithm is that its *computational and memory* requirements can grow with time and saturate computing system.
- **Solution:** Only a limited number of the nearest hits in the validation gate can start a new branch.

Maximum number of hits in the validation gate	30	20	15	10	7	5	4	3	2	1
Tracking efficiency, %	93.1	93.1	93.1	93.1	93.1	93.1	93.1	92.9	92.9	91.8
Time, s/event	1.9						0.52	0.44	0.34	0.20

**4 times faster!**

MUCH tracking, UrQMD 25 AGeV Au-Au + 10 muons

CPU: Intel C2D P8400

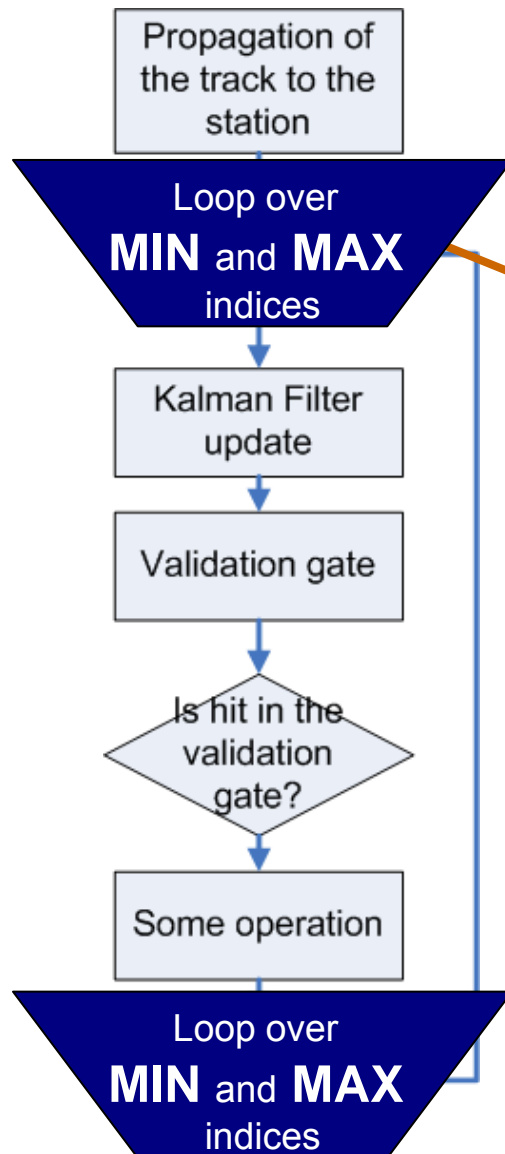
# Speed up [2]: fast search of hits

## Motivation

- Hits are sorted by x position
- Binary search is used to find Min and Max index

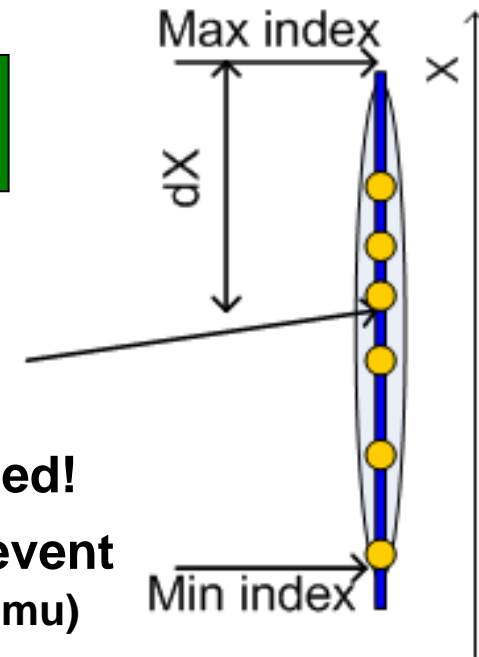
$$dX = k\sqrt{\sigma_{cov}^2 + \sigma_{pos}^2}$$

$\sigma_{pos}$  Maximum measurement error on the station



Fast search of hits

**2** times increase in speed!  
1.05 s/event -> **0.52** s/event  
(MUCH tracking, UrQMD+10mu)

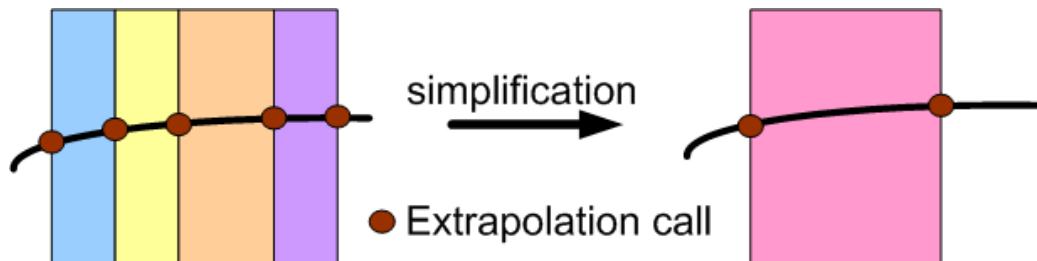


CPU: Intel C2D P8400

# Speed up [3]: simple geometry

- MC geometry
  - Very detailed (800k nodes)
  - Navigation is based on the ROOT TGeo
- Simplified geometry
  - There is no need for detailed geometry for tracking purposes
  - Stations and passive materials are approximated as planes perpendicular to beam pipe
    - Reduction of number of nodes from 800k to 100
  - Navigation in such geometry is much more simple

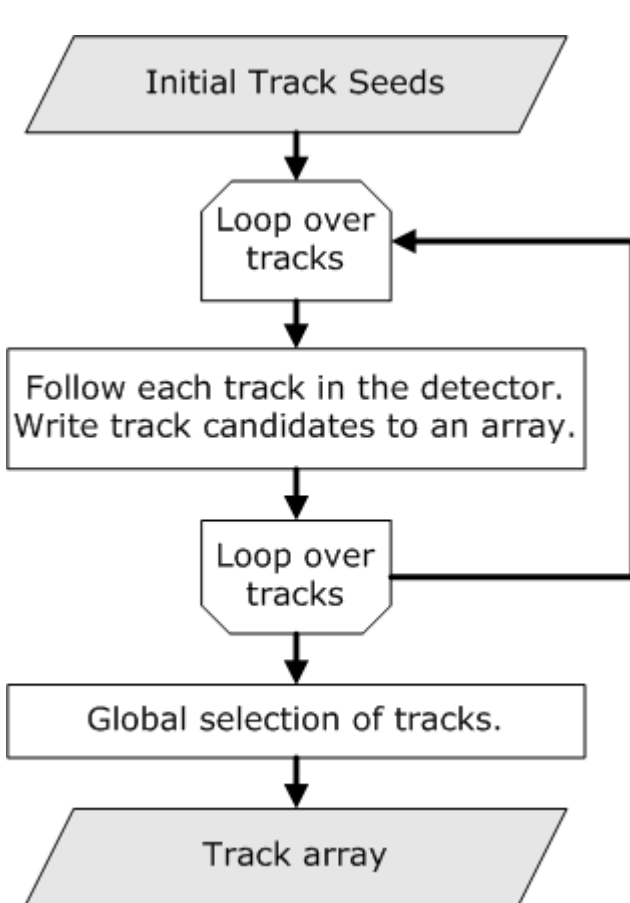
	Efficiency [%] / time [sec/event]		Speed up factor
	ROOT TGeo	Simplified	
Branching	<b>94.9 / 0.88</b>	<b>94.0 / 0.20</b>	<b>4.4</b>
NN	<b>92.6 / 0.20</b>	<b>92.2 / 0.06</b>	<b>3.3</b>
Weighting	<b>94.0 / 0.31</b>	<b>92.6 / 0.11</b>	<b>2.8</b>



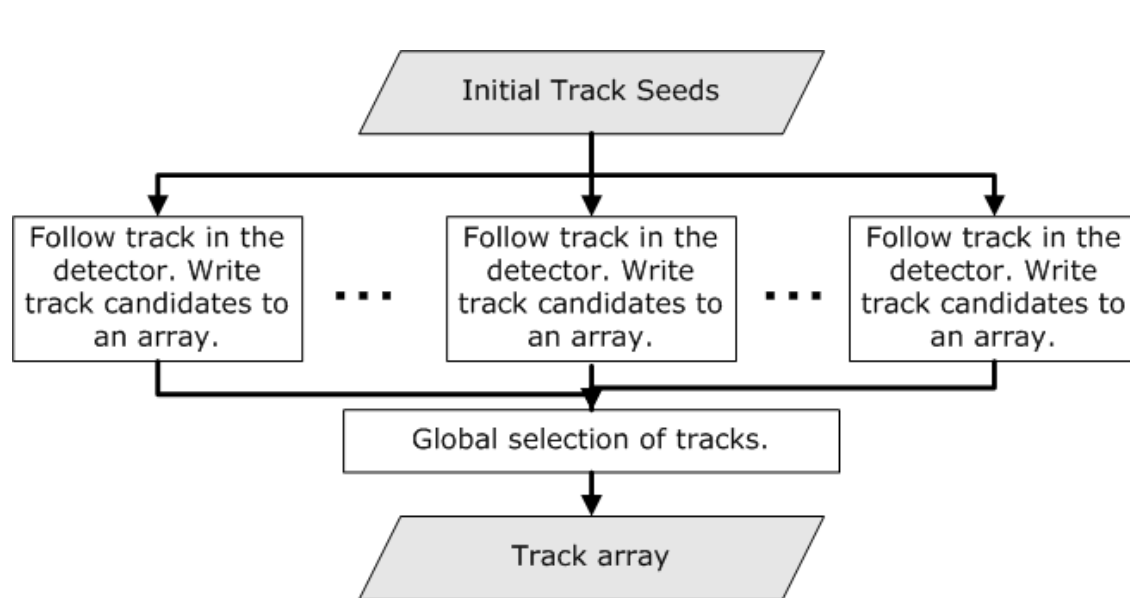
CPU: Intel C2D P8400

# Multithreading for track following

Serial



Parallel



Library: *Intel Threading Building Blocks*

CPU: Intel C2D P8400 with **2 cores**

**serial and parallel nearest neighbor method:**

Serial: **0.06** sec/event

Parallel: **0.04** sec/event

**Speed up factor: 1.59**

# Summary & Outlook

- Successfully demonstrated that developed global tracking approaches are feasible with current CBM layout in a high track density
  - First results of speed up show 20 times speed up factor
- continue speed up optimization of the algorithm (SIMD, multithreading, magnetic field access...)
- use established tracking routines for layout optimization