Identification of Internal Points of Macromolecular System for Statement of Parameters of Poisson-Boltzmann Equation

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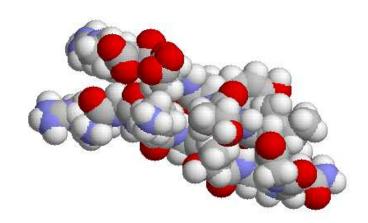


Figure 1: The 14-residue peptide rg-kwty-ng-itye-gr

Nonlinear Poisson-Boltzmann equation for electrostatic potential u:

$$-\nabla \cdot \left[\varepsilon(\vec{r}) \, \nabla u(\vec{r}) \right] + k^2(\vec{r}) \, \sinh \left[u(\vec{r}) \right] = \frac{4\pi e_c^2}{k_B T} \sum_{i=1}^{N_m} z_i \, \delta(\vec{r} - \vec{r}_i),$$

$$u(\infty)=0,$$
 dielectric constant $\varepsilon=\left\{ egin{array}{ll} 2 \ \mbox{inside molecule,} \\ 80 \ \mbox{in water.} \end{array}
ight.$

The existence of cavities should be taken into account when solving different problems connected to the molecular properties.







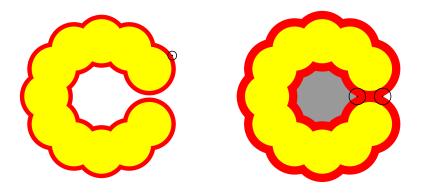


Figure 2: A molecule (yellow) without (left) and with (right) a cavity

Different positions of a point:¹

- 1. The point is outside of the molecule's envelope (inside solvent accessible volume) white color.
- 2. The point is inside of some molecule's atom yellow color.
- 3. The point is outside a molecule, but inside its neighborhood of size equal to the solvent radius red color.
- 4. The point is inside a molecule's cavity gray color.







¹The cavity existence depends on the probe spheres radius.

2D inspiration of triangulation

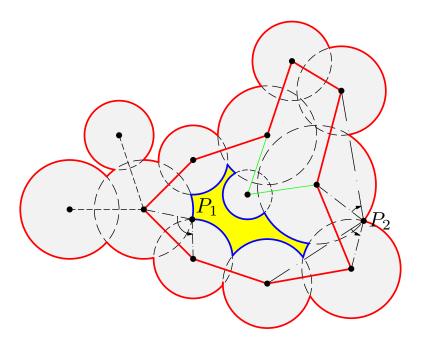


Figure 3: 2D analogy for triangulation

The sum of oriented angles for an internal point P_1 is equal 2π rad (in 3D 4π steradian), for an external point P_2 it is equal 0.

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44

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Let $\mathcal{M} = \bigcup_{i=1}^{N} \mathcal{S}_i$ be a finite union of spheres in E_3 — \mathcal{M} is a molecule's model, in which atoms are represented by spheres.

Definition 1 The triangle $\Delta C_1 C_2 C_3$ of centres of spheres of \mathcal{M} is a wall triangle in \mathcal{M} if and only if the intersection $\delta \mathcal{S}_1 \cap \delta \mathcal{S}_2 \cap \delta \mathcal{S}_3$ of the surfaces of the spheres consists just of one or two points, and at least one of them is external, it does not lie in Int \mathcal{M} .

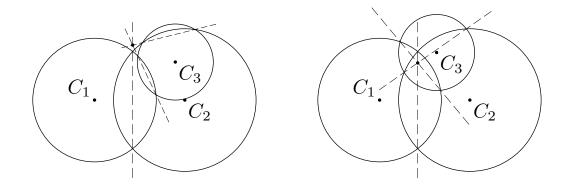


Figure 4: Nonwall and wall triangles





Definition 2 A cavities enveloping triangulation $\Delta \mathcal{M}$ (briefly envelope triangulation) of a finite system of spheres \mathcal{M} is either an empty set or it is such a set of wall triangles in \mathcal{M} with coincident orientation that

- (i) $\Delta \mathcal{M}$ forms a family of polyhedral \mathcal{P}_i with wall triangles at post of faces oriented inward such that $\operatorname{Int} \mathcal{P}_i \cap \operatorname{Int} \mathcal{P}_j = \emptyset$, for all $i \neq j$,
- (ii) any cavity point lies inside of some of these polyhedrons,
- (iii) if a point from $E_3 \mathcal{M}$ is not included in any cavity of \mathcal{M} , it lies outside of the triangulation $\Delta \mathcal{M}$.

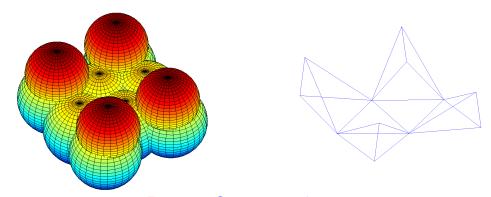
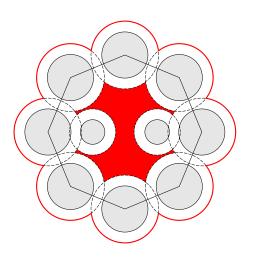


Figure 5: Cavity triangulation







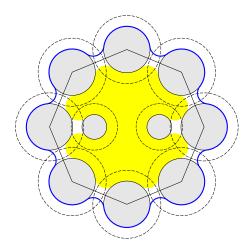


Figure 6: Two different definitions of the cavity volume. The molecule's atoms are lightgray. Red area in the left picture represents the volume of the part of the space, where the center of "water atom" can be put. The yellow right cavity volume [3] is the "volume of the water" included inside the molecule. Molecular surface [3] is blue. The definitions are equivalent if the probe radius $r_p = 0$.

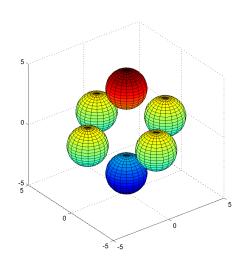
- The solvent accessible surface introduced by Lee and Richards [1], and Chothia [2], is traced out by the probe sphere center as the sphere rolls over the molecular surface of the protein.
- The solvent-excluded or inaccessible volume is the volume contained within the solvent accessible surface.

44





Numerical result



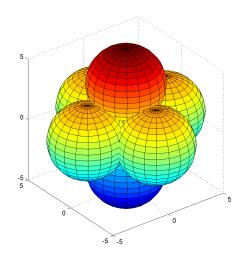


Figure 7: 6 atoms from file jan6.pdb – $r_a=1.501$, $r_w=1.401$

MOTA	1	0	MET	41	3.500	0.000	0.000	2.00	2.04	0
ATOM	2	0	MET	41	0.000	3.500	0.000	2.00	2.04	0
MOTA	3	0	MET	41	0.000	0.000	3.500	2.00	2.04	0
MOTA	4	0	MET	41	-3.500	0.000	0.000	2.00	2.04	0
MOTA	5	0	MET	41	0.000	-3.500	0.000	2.00	2.04	0
MOTA	6	0	MET	41	0.000	0.000	-3.500	2.00	2.04	0



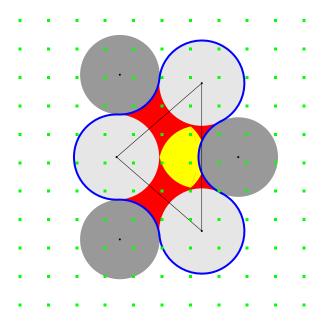


Figure 8: Space inside of the molecular surface: molecule (gray), between two molecula (red), between three molecula, inside a cavity (yellow)

Number of internal points (h = 0.5 Å, total number of grid points is $65 \times 65 \times 65 = 274625$):

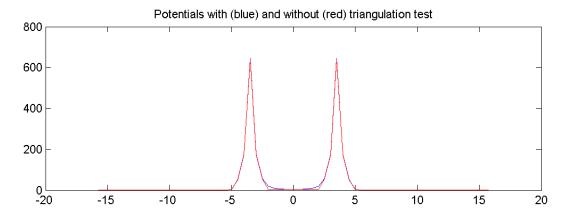
nxi: 660 32 0 200 nyi: 660 32 0 200 nzi: 660 32 0 200

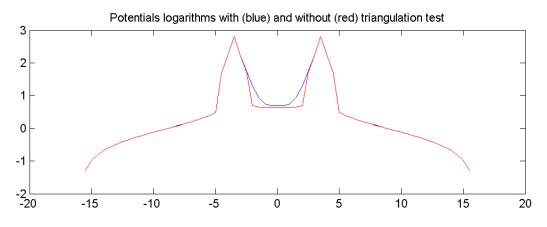






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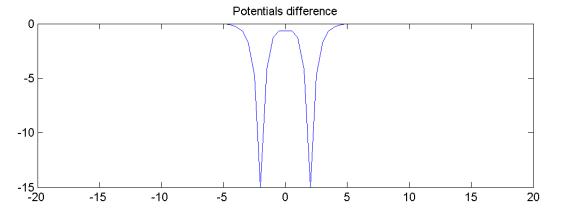


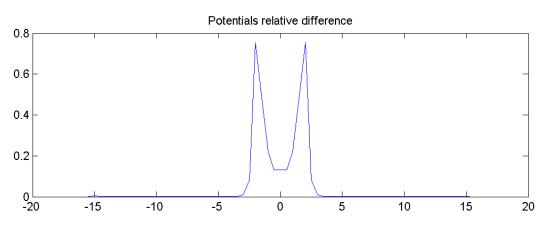


















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Conclusions

Pro: The cavity triangulation construction and its usage for the triangulation test may lead to more realistic values of the electrostatic potential and corresponding energies (we suppose, that the DelPhi program doesn't include such a test).

Contra: Our algorithm and program is nowadays not very efficient, the calculation time with the triangulation test included is sufficient larger than the time without the test.







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Back

Close

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Back Close

15/51

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The surface area of a spherical triangle

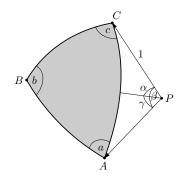


Figure 9: The surface area of the spherical triangle

A spherical angle is the surface area of the unit sphere's triangle:

$$\sigma(\Delta ABC) = A + B + C - \pi,\tag{1}$$

where the arc lengths $\alpha = \angle BPC$, β , γ (angular lengths) and vertex angles A, B, and C of the triangle in Figure 9 are related by the following cosine formula

$$\cos \alpha = \cos \beta \, \cos \gamma + \sin \beta \, \sin \gamma \, \cos A \tag{2}$$

and its next two permutations by variables (see, e.g., [11, 12, 13]).





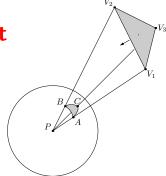


Figure 10: Cavity indexing

Definition 3 Let P be a point of E_3 not belonging to the cavity triangulation $\Delta \mathcal{M}$. The index of P with respect to the cavity triangulation $\Delta \mathcal{M}$ is the number

$$\chi_P(\Delta \mathcal{M}) = \frac{1}{4\pi} \sum_{\delta \in \Delta \mathcal{M}} \sigma_P(\delta).$$

Proposition 1 An envelope triangulation $\Delta \mathcal{M}$ contains the point P (different from vertices of triangulation) inside itself if and only if

$$\chi_P(\Delta \mathcal{M}) = 1.$$







18/51

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The **first class** of points which are indicated by value 1 are internal points of the van der Walls area. These points X=(x,y,z) are inside of some balls \mathcal{B}_i and accordingly satisfy the inequality

$$||X - C_i|| < r_i \text{ for some ball } \mathcal{B}_i \tag{1}$$

where
$$||X - C_i|| = \sqrt{(x - x_i)^2 + (y - y_i)^2 + (z - z_i)^2}$$
.



The **second class** consists of such points X=(x,y,z) that there are two different balls \mathcal{B}_i and \mathcal{B}_j that are close to point X and each to other less than diameter $2r_s$ of the solvent sphere. So, they satisfy inequalities

$$||X - C_m|| < r_m + 2r_s \text{ for each } m \in \{i, j\}$$
 (a) $||C_i - C_j|| < r_i + r_j + 2r_s.$

If the solvent ball is rolling over balls \mathcal{B}_i , \mathcal{B}_j and touching both, it designs a torus (potentially degenerate). Connecting lines of the solvent center and centers of balls \mathcal{B}_i and \mathcal{B}_j design two conical surfaces. For some couple of balls \mathcal{B}_i , \mathcal{B}_j satisfying (a), the point X is inside of both cones (with the scalar product of vectors on the left side) and outside of the







 $(X - C_i) \cdot (C_j - C_i) > \frac{\|C_j - C_i\|^2 + (r_i + r_s)^2 - (r_j + r_s)^2}{2(r_i + r_s)} \|X - C_i\|$

$$||X - D_{ij}||^2 + R_{ij}^2 > 2R_{ij}\operatorname{dist}\left(X, \overleftarrow{C_iC_j}\right) + r_s^2$$

20/51

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Back Close

where

torus

and

$$D_{ij} = C_i + \left(\frac{1}{2} + \frac{(r_i + r_s)^2 - (r_j + r_s)^2}{2 \|C_i - C_i\|^2}\right) (C_j - C_i)$$

 $R_{ij} = \sqrt{\frac{(r_i + r_s)^2 + (r_j + r_s)^2}{2} - \frac{\|C_j - C_i\|^2}{4} - \frac{((r_i + r_s)^2 - (r_j + r_s)^2)^2}{4\|C_i - C_i\|^2}}$

are the center and the radius of the torus. The distance X from the

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axis of rotation $\overrightarrow{C_iC_j}$ of the torus is

$$\operatorname{dist}\left(X, \overleftarrow{C_i}\overrightarrow{C_j}\right) = \frac{\|(X - C_i) \times (C_j - C_i)\|}{\|C_j - C_i\|}$$

(with the vector product in the numerator). Membership in several classes is possible.





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If point X = (x, y, z) belongs to the **third class** then there are three different balls \mathcal{B}_i , \mathcal{B}_j , \mathcal{B}_k generating a wall triangle that are close to point X less than $2r_s$. So, it satisfies inequalities

$$||X - C_m|| < r_m + 2r_s \text{ for each } m \in \{i, j, k\}.$$
 (b)

The point X is outside solvent spheres positioned by their centers in E_{ijk} and E'_{ijk} but inside one of tetrahedrons $C_iC_jC_kE_{ijk}$ and $C_iC_jC_kE'_{ijk}$. So, X - E is a convex combination of $C_i - E$, $C_j - E$ and $C_k - E$.

$$||X - E|| > s$$

$$\alpha_m \ge 0 \text{ and } \sum_{m=1}^{3} \alpha_m \le 1$$
(3)

where

$$X - E = \alpha_1(C_i - E) + \alpha_2(C_i - E) + \alpha_3(C_k - E)$$

for some triplet \mathcal{B}_i , \mathcal{B}_j , \mathcal{B}_k satisfying (b) and E_{ijk} or E'_{ijk} in role E.







Close